

Towards Abstraction Refinement in TVLA

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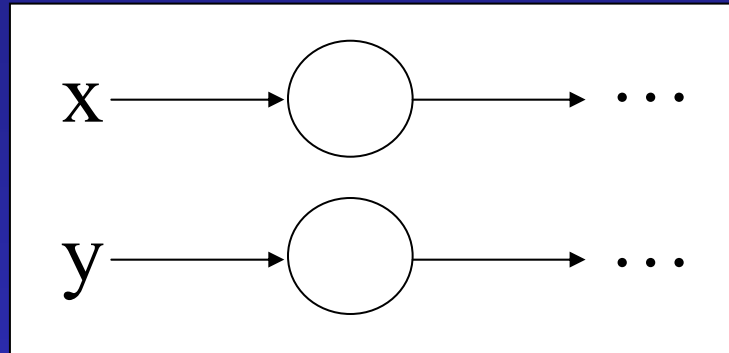
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Need for Heap Data Analysis

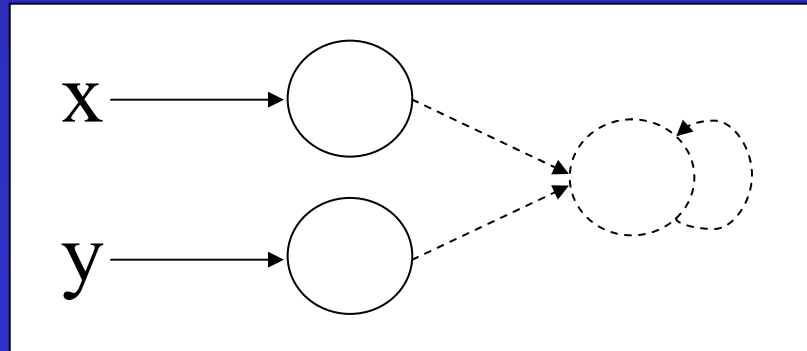
- Morning talks by UW students
 - Static analyses for de-obfuscation of code
 - Limited ability to analyze heap data
 - Need understanding of possible shapes
 - Want to handle unbounded heap object creation
 - Java objects (e.g. threads) are in heap

Linked List Abstractions

- Informally

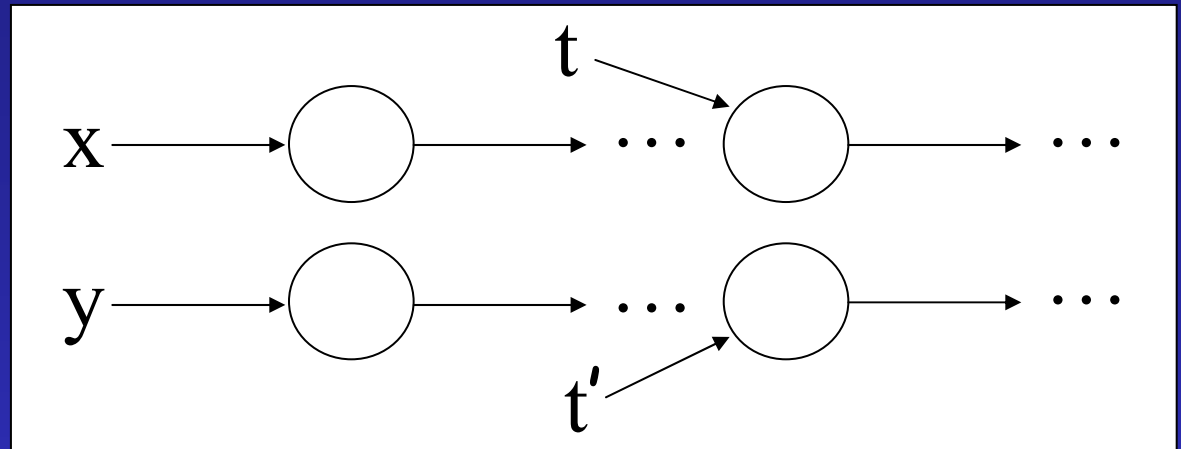


- Formally

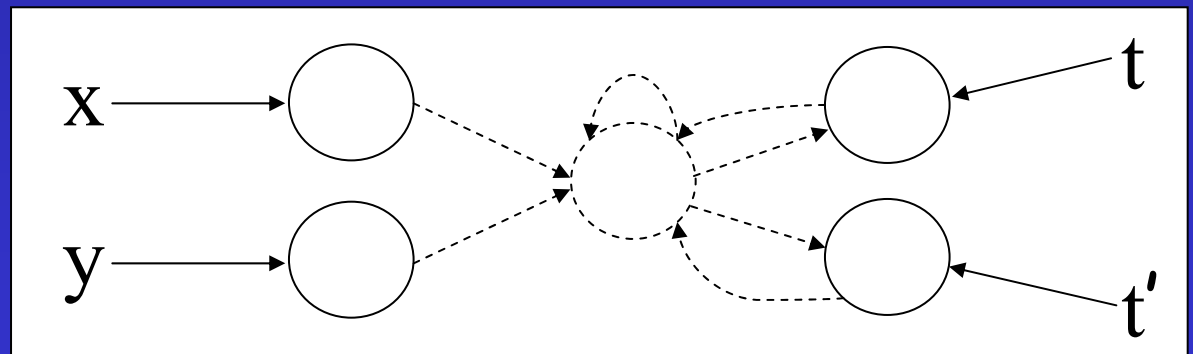


Linked List Abstractions

- Informally

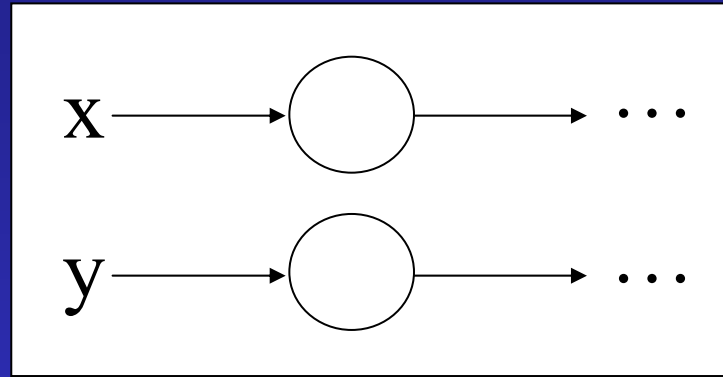


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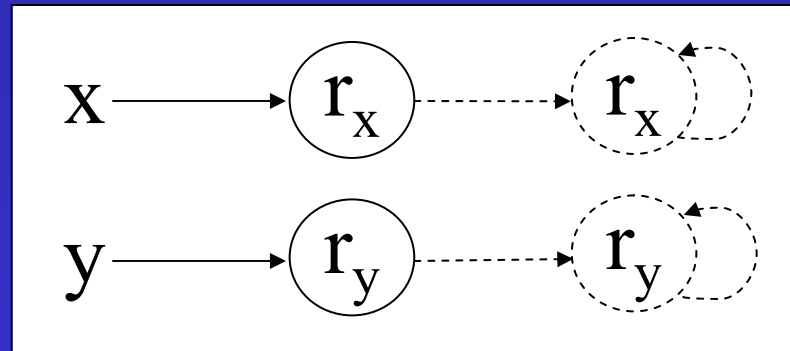


Linked List Abstractions

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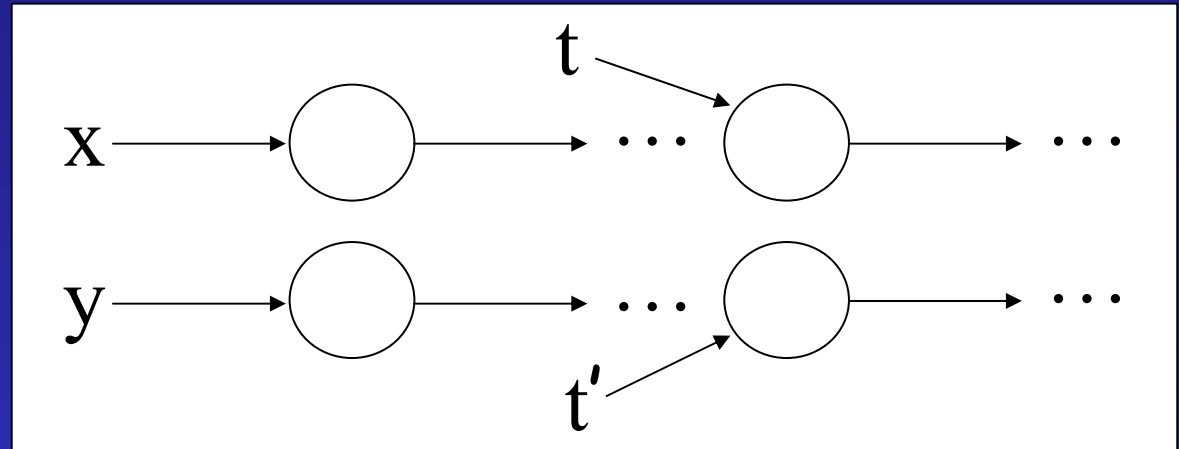


- Formally

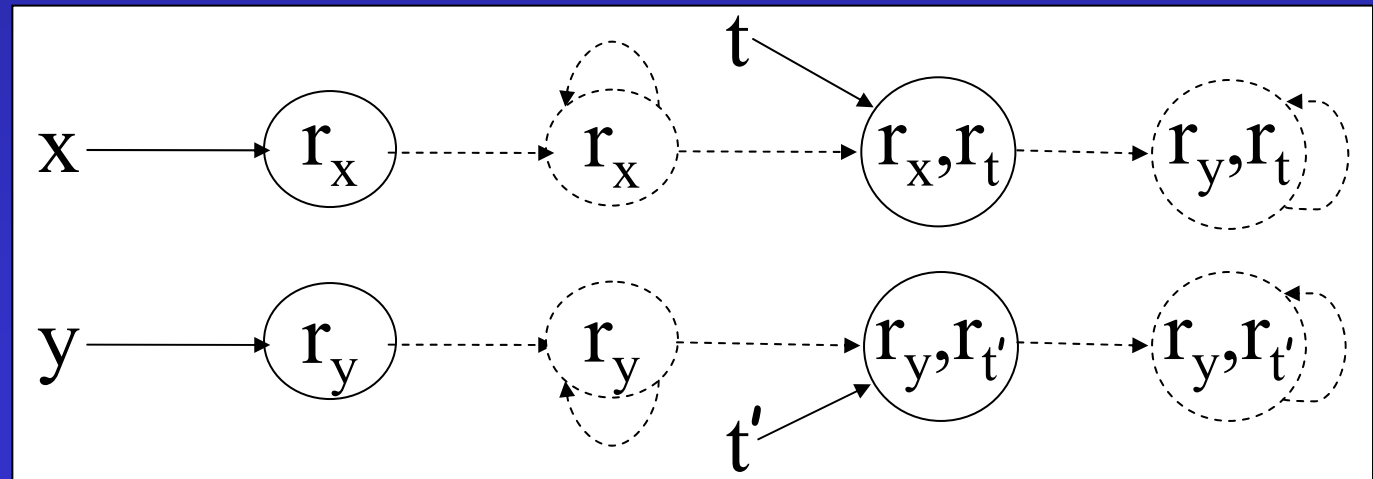


Linked List Abstractions

- Informally



- Formally



Abstraction Refinement

- Devising good analysis abstractions is hard
 - Precision/cost tradeoff
 - Too coarse: “Unknown” answer
 - Too refined: high space/time cost
- Start with simple (and cheap) abstraction
- Successively refine abstraction
 - Adaptive algorithm

Abstraction Refinement

- Iterative process
 - Create an abstraction (e.g. set of predicates)
 - Run analysis
 - Detect indefinite answers (stop if none)
 - Refine abstraction (e.g. add predicates)
 - Repeat above steps

Previous Work on Abstraction Refinement

- Counterexample guided [Clarke et al]
 - Finds shortest invalid prefix of spurious counterexample
 - Splits last state on prefix into less abstract ones
- SLAM toolkit [Ball, Rajamani]
 - Temporal safety properties of software
 - Identifies correlated branches

Abstraction Refinement for TVLA: New Challenges

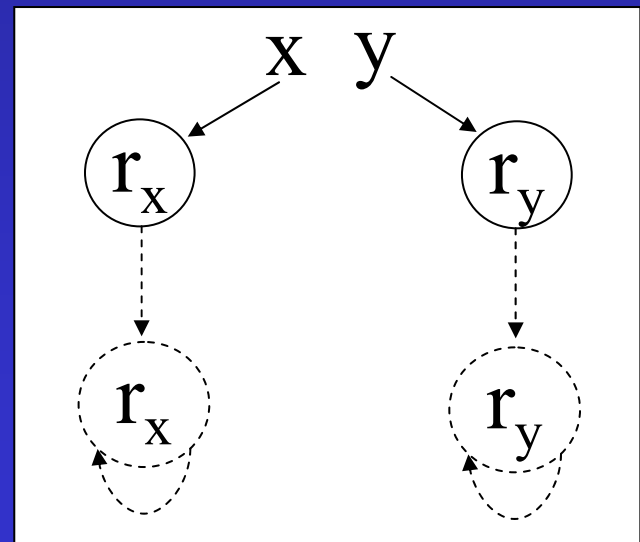
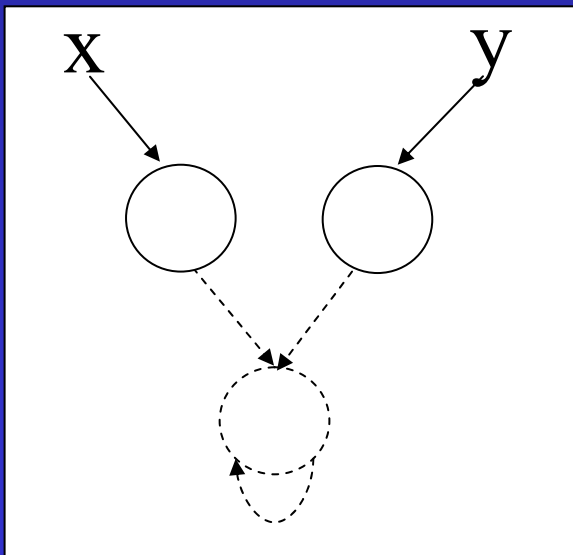
- Need to refine abstractions of linked data structures
 - Identify appropriate new distinctions between
 - Nodes
 - Structures
- Need to derive the associated abstract interpretation
 - What are the update formulas?

Control Over the Merging of Nodes

- Unary abstraction predicates

$$r_x(v) = \exists v' : (x(v') \rightarrow n^*(v', v))$$

- Distinguish nodes reachable from x (and y)
- Can now tell if lists are disjoint

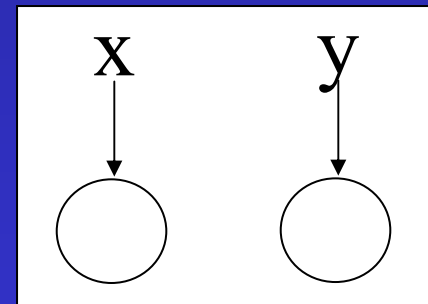
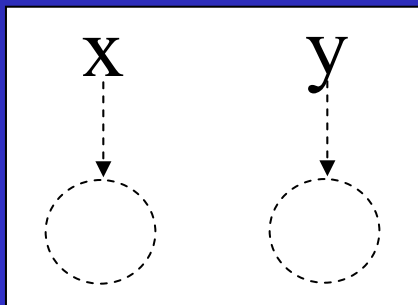


Control Over the Merging of Structures

- Nullary abstraction predicates

$$nn_x() = \exists v : x(v)$$

- Distinguish structures based on whether x is NULL
- Can now tell that x is NULL whenever y is (and vice versa)



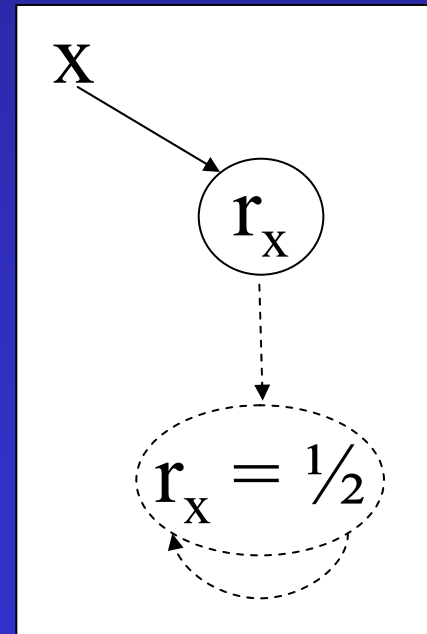
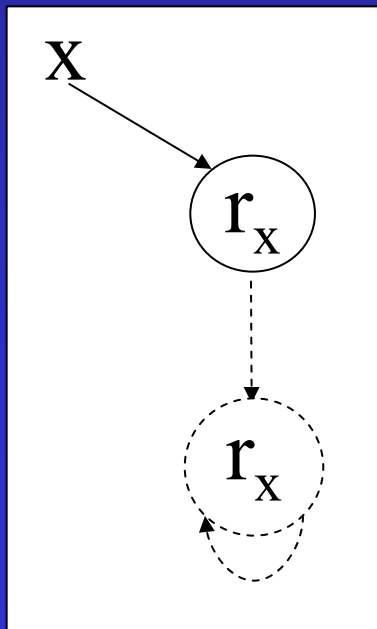
empty structure

Need for Update Formulas

- Re-evaluating formula is imprecise

$$r_x(v) = \exists v' : (x(v') \xrightarrow{n^*} n^*(v',v))$$

Action “ $x == \text{NULL}$ ” (no change to heap)



Creating Update Formulas Automatically

- Frees user from having to provide update formulas
 - A lot of work (esp. with iterative refinement)
 - Error prone
- Idea: Finite differencing of formulas

$$F(\varphi) = p_{\varphi} \otimes \varphi^{\Delta}$$

Differencing \approx Differentiation

$$0^\Delta = 0$$

$$1^\Delta = 0$$

$$(\varphi \oplus \psi)^\Delta = \varphi^\Delta \oplus \psi^\Delta$$

$$(\varphi \otimes \psi)^\Delta = \varphi \otimes \psi^\Delta + \varphi^\Delta \otimes \psi$$

$$c' = 0$$

$$(f+g)'(x) = f'(x)+g'(x)$$

$$(f * g)'(x) = f'(x) * g(x) + f(x) * g'(x)$$

Laws for φ^Δ

$$0^\Delta = 0$$

$$1^\Delta = 0$$

$$(v = w)^\Delta = 0$$

$$(\varphi \multimap \psi)^\Delta = \varphi^\Delta \multimap \psi^\Delta$$

$$(\varphi \multimap \psi)^\Delta = \varphi \multimap \psi^\Delta \multimap \varphi^\Delta \multimap \psi \multimap \varphi^\Delta \multimap \psi^\Delta$$

$$(\Downarrow v:\varphi)^\Delta = (\Downarrow v:\varphi) \multimap (\Downarrow v:\varphi \multimap \varphi^\Delta)$$

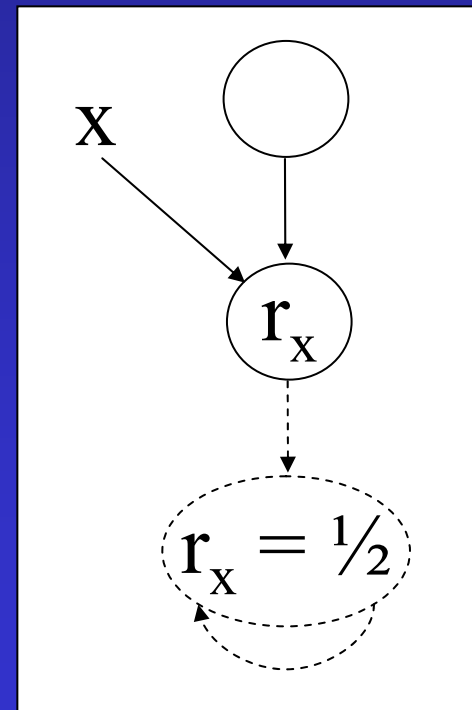
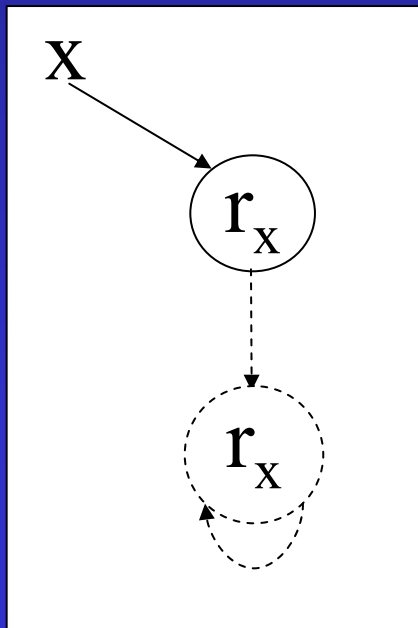
$$(TC:\varphi)(v,w)^\Delta = (TC:\varphi)(v,w) \multimap (TC:\varphi \multimap \varphi^\Delta)(v,w)$$

Formula Differencing Limitations

- Differencing output often imprecise

$$r_x(v) = \exists v' : (x(v') \rightarrow n^*(v', v))$$

Action “ $x = x \rightarrow n$ ”

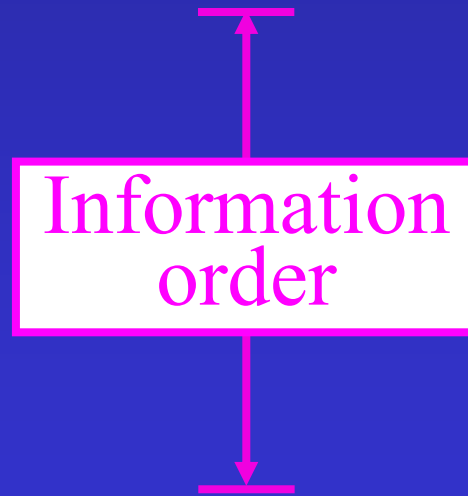
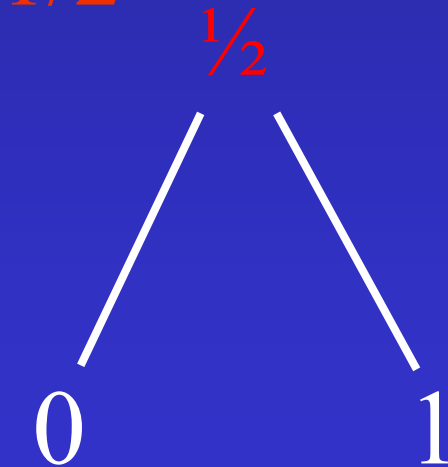


Reducing Loss of Precision from Differencing

- Semantic minimization of formulas
 - Simplest case: propositional formulas
- Work in progress
 - Removing unnecessary reevaluation
 - Finding common sub-formulas
 - Improvements to materialization
 - Exploiting important special cases
 - E.g., reachability in lists

Three-Valued Logic

- 1: True
- 0: False
- $1/2$: Unknown
- A join semi-lattice: $0 \sqcup 1 = 1/2$



$$0 \preceq 1/2$$
$$1 \preceq 1/2$$

Semantic Minimization

- $\leftarrow \varphi \rightarrow(A)$: Value of formula φ under assignment A
- In 3-valued logic, $\leftarrow \varphi \rightarrow(A)$ may equal $\frac{1}{2}$

$$\leftarrow p + p' \rightarrow([p \approx 0]) = 1$$

$$\leftarrow p + p' \rightarrow([p \approx \frac{1}{2}]) = \frac{1}{2}$$

$$\leftarrow p + p' \rightarrow([p \approx 1]) = 1$$

- However,

$$\leftarrow 1 \rightarrow([p \approx 0]) = 1$$

$$\leftarrow 1 \rightarrow([p \approx \frac{1}{2}]) = 1$$

$$\leftarrow 1 \rightarrow([p \approx 1]) = 1$$

Semantic Minimization

$$\begin{aligned} \leftarrow 1 \rightarrow ([p \approx 0]) = 1 &= \leftarrow p + p' \rightarrow ([p \approx 0]) \\ \leftarrow 1 \rightarrow ([p \approx \frac{1}{2}]) = 1 \sqcap \frac{1}{2} &= \leftarrow p + p' \rightarrow ([p \approx \frac{1}{2}]) \\ \leftarrow 1 \rightarrow ([p \approx 1]) = 1 &= \leftarrow p + p' \rightarrow ([p \approx 1]) \end{aligned}$$

2-valued logic: 1 is equivalent to $p + p'$

3-valued logic: 1 is **better than** $p + p'$

For a given φ , is there a best formula?

Yes!

Minimal?

$x + x'$	No!
$x \oplus x'$	Yes!
$xy + x'z$	No!
$xy + x'y'$	Yes!
$xy + x'z + yz$	Yes!
$xy' + x'z' + yz$	No!

Example

Original formula (φ)

$$xy + x'z$$

Minimal formula (ψ)

$$xy + x'z + yz$$

A	$\leftarrow\psi\rightarrow(A)$	$\leftarrow\varphi\rightarrow(A)$
$[x \approx \frac{1}{2}, y \approx 1, z \approx 1]$	1	$\frac{1}{2}$

Example

Original formula (φ)

$$xy' + x'z' + yz$$

Minimal formula (ψ)

$$x'y + x'z' + yz + xy' + xz + y'z'$$

A	$\leftarrow\psi\rightarrow(A)$	$\leftarrow\varphi\rightarrow(A)$
$[x \approx \frac{1}{2}, y \approx 0, z \approx 0]$	1	$\frac{1}{2}$
$[x \approx 0, y \approx 1, z \approx \frac{1}{2}]$	1	$\frac{1}{2}$
$[x \approx 1, y \approx \frac{1}{2}, z \approx 1]$	1	$\frac{1}{2}$

Semantic Minimization

- When φ contains no occurrences of $\frac{1}{2}$ and $\tilde{\square}$

$$\square \text{primes}(\leftarrow \varphi \rightarrow)$$

- In general, somewhat more complicated

- Represent $\leftarrow \varphi \rightarrow$ with a pair

$$0 \quad \text{floor:} \quad \mathbb{Q} \leftarrow \varphi \rightarrow \mathcal{D} \quad \mathbb{Q}^{\frac{1}{2}} \mathcal{D} =$$

$$1 \quad \text{ceiling:} \quad \mathbb{Q} \leftarrow \varphi \rightarrow \mathcal{D} \quad \mathbb{Q}^{\frac{1}{2}} \mathcal{D} =$$

- Semantically minimal formula

Current and Future Work

- Finite differencing of formulas
- Minimization of first-order formulas
- Generation of instrumentation predicates

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