Provisioning Cloud-Based Computing Resources via a Dynamical Systems Approach

Marty Kandes

University of California, San Diego

May 18, 2016

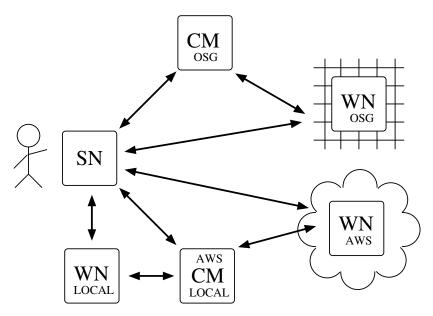
< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Objective

Build a service for provisioning cloud-based computing resources that can be used to augment users' existing, fixed resources and meet their batch job demands.

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

Vision



condor_annex is a Perl-based script that utilizes the AWS CLI and other AWS services to orchestrate the delivery of HTCondor execute nodes from the cloud to your HTCondor pool.

Some key features:

- Supports bidding for spot instances.
- Instances sitting idle, not running user jobs will terminate after a fixed idle time (20 min).

• Each "annex" itself also has a finite lifetime.

My Problem

How many instances do I order with condor_annex to meet current user job demand?

◆□ ▶ < 圖 ▶ < 圖 ▶ < 圖 ▶ < 圖 • 의 Q @</p>

My Original Assumptions

Known knowns:

- Idle instances terminate after a fixed lifetime (20min)
- Instances terminate when annex lease expires
- Assume (for now) single-core user jobs and instances

Known unknows:

- User jobs arrive in queue at some unknown rate
- More user jobs than instances that can be purchased
- User jobs flock away to "free" resources at some unknown rate

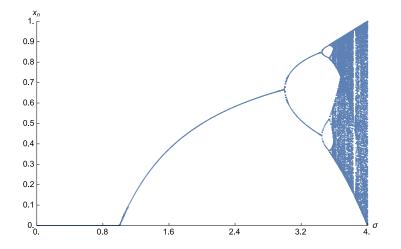
- User job runtimes are unknown at submission
- Spot instances are preempted at some unknown rate
- Spot prices vary with time

Optimization Problem vs. Control Problem

- Forget optimally scheduling jobs and resources; too hard.
- Instead, seek to provision resources in a controlled way.
- Build a system that aims to use resources safely and efficiently.

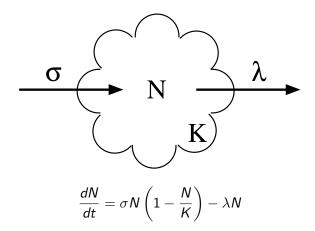
< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Simple System \Rightarrow Simple Dynamics



Logistic Map: $x_{n+1} = \sigma x_n (1 - x_n)$, where $0 \le x_0 \le 1$.

An Oversimplified Provisioning Model



◆□ > ◆□ > ◆豆 > ◆豆 > ̄豆 = のへで

Dynamical Systems 101

$$\frac{dN}{dt} = f(N) = \sigma N \left(1 - \frac{N}{K} \right) - \lambda N$$

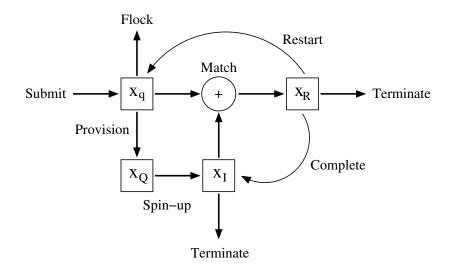
1. Find equilibria. Set $\frac{dN}{dt} = 0$ and solve for N^* .

$$\sigma N^* \left(1 - \frac{N^*}{\kappa} \right) - \lambda N^* = 0 \implies N^* = 0, \kappa \left(1 - \frac{\lambda}{\sigma} \right)$$

2. Check stability of equilibria.

$$\begin{aligned} \frac{df}{dN} &= \sigma - 2\sigma \frac{N}{K} - \lambda \\ \frac{df}{dN} \bigg|_{N^* = 0} &= \sigma - \lambda < 0 \iff \sigma < \lambda \\ \frac{df}{dN} \bigg|_{N^* = K\left(1 - \frac{\lambda}{\sigma}\right)} &= \lambda - \sigma < 0 \iff \sigma > \lambda \end{aligned}$$

Provisioning Model I: State Diagram



◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

Provisioning Model I: System of Equations

$$\frac{dx_q}{dt} = \Sigma_q - \sigma_{IR} x_q x_I - \sigma_{qf} x_q + \sigma_{Rq} x_R$$

$$\frac{dx_Q}{dt} = \sigma_{qQ} x_q - \sigma_{QI} x_Q$$

$$\frac{dx_I}{dt} = \sigma_{QI} x_Q - \sigma_{IR} x_q x_I + \sigma_{RI} x_R - \sigma_{IT} x_I$$

$$\frac{dx_R}{dt} = \sigma_{IR} x_q x_I - \sigma_{RI} x_R - \sigma_{Rq} x_R - \sigma_{RT} x_R$$

Provisioning Model I: Definitions

- x_q = number of user jobs in the queue
- x_Q = number of instances in the queue
- x_I = number of instances sitting idle
- x_R = number of instances busy running user jobs
- Σ_q = rate of user job submission (jobs/time)
- $\sigma_{I\!R} = 1/\tau_{I\!R} =$ matchmaking rate; $\tau_{I\!R} =$ idle-running lifetime
- ▶ $\sigma_{qf} = 1/\tau_{qf}$ = flocking rate; τ_{qf} = flocking lifetime
- $\sigma_{Rq} = 1/\tau_{Rq}$ = restart rate; τ_{Rq} = restart lifetime
- $\sigma_{qQ} =$ queueing rate
- ▶ $\sigma_{QI} = 1/\tau_{QI}$ = instance spin-up rate; τ_{QI} = annex start-up time
- $\sigma_{RI} = 1/\tau_{RI} = \text{job completion rate}; \ \tau_{RI} = \text{job lifetime}$
- $\sigma_{IT} = 1/\tau_{IT}$ = idle termination rate; τ_{IT} = idle-termination lifetime
- $\sigma_{RT} = 1/\tau_{RT}$ = running termination rate; τ_{RT} = annex lifetime

Provisioning Model I: Equilibria

Solve.

$$\frac{dx_q}{dt} = f_q(x_q, x_Q, x_I, x_R) = 0$$
$$\frac{dx_Q}{dt} = f_Q(x_q, x_Q, x_I, x_R) = 0$$
$$\frac{dx_I}{dt} = f_I(x_q, x_Q, x_I, x_R) = 0$$
$$\frac{dx_R}{dt} = f_R(x_q, x_Q, x_I, x_R) = 0$$

Find two equilibrium points.

$$\mathbf{x}_{1}^{*} = (x_{q_{1}}^{*}, x_{Q_{1}}^{*}, x_{I_{1}}^{*}, x_{R_{1}}^{*})$$
$$\mathbf{x}_{2}^{*} = (x_{q_{2}}^{*}, x_{Q_{2}}^{*}, x_{I_{2}}^{*}, x_{R_{2}}^{*})$$

(ロ)、(型)、(E)、(E)、 E) の(の)

Provisioning Model I: Stability of Equilibria

Find Jacobian.

$$J = \frac{d\mathbf{f}}{d\mathbf{x}} = \begin{bmatrix} \frac{df_q}{dx_q} & \frac{df_q}{dx_Q} & \frac{df_q}{dx_l} & \frac{df_q}{dx_R} \\ \frac{df_Q}{dx_q} & \frac{df_Q}{dx_Q} & \frac{df_Q}{dx_l} & \frac{df_Q}{dx_R} \\ \frac{df_I}{dx_q} & \frac{df_I}{dx_Q} & \frac{df_I}{dx_l} & \frac{df_I}{dx_R} \\ \frac{df_R}{dx_q} & \frac{df_R}{dx_Q} & \frac{df_R}{dx_l} & \frac{df_R}{dx_R} \end{bmatrix}$$

Compute eigenvalues of Jacobian about \mathbf{x}_1^* and \mathbf{x}_2^* .

$$\mathbf{f}(\mathbf{x}) = \mathbf{f}(\mathbf{x}^*) + J(\mathbf{x}^*)(\mathbf{x} - \mathbf{x}^*) + \cdots$$

If the eigenvalues all have real parts that are negative, then the system is **stable** near the stationary point, if any eigenvalue has a real part that is positive, then the point is **unstable**.

Validation Test I: Parameters

►
$$x_q(t=0) = x_Q(t=0) = x_I(t=0) = x_R(t=0) = 0$$

- $\Sigma_q = 60$ jobs per hour
- $\sigma_{I\!R} = 1/\tau_{I\!R} = 1$ / 5 minutes
- $\sigma_{qf} = 0$ (No flocking)
- $\sigma_{Rq} = 0$ (No restarts)

•
$$\sigma_{qQ} = 0.1$$

•
$$\sigma_{QI} = 1/\tau_{QI} = 1 / 10$$
 minutes

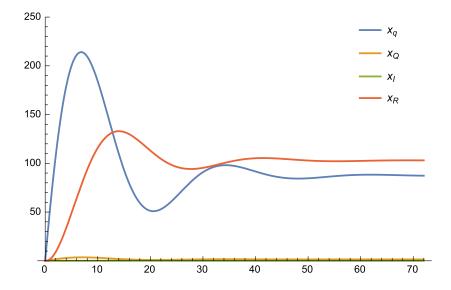
•
$$\sigma_{RI} = 1/\tau_{RI} = 1 / 2$$
 hours

•
$$\sigma_{IT} = 1/\tau_{IT} = 1 / 20$$
 minutes

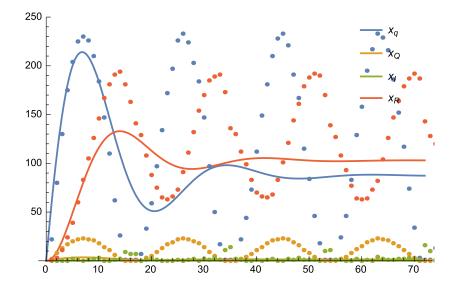
•
$$\sigma_{RT} = 1/\tau_{RT} = 1 / 12$$
 hours

- ▶ $\mathbf{x}_1^* = (-1.71566, -0.0285943, 2.91433, 102.857)$
- ▶ $\mathbf{x}_2^* = (87.4299, 1.45717, 0.0571886, 102.857)$
- ► $\lambda_1 = (54.4891, -5.9492, -1.98, -0.583333)$
- ► $\lambda_2 = (-1052.84, -5.89802, -0.583333, -0.103362)$

Validation Test I: Simulation Results (72 Hours)



Validation Test I: Experimental Results (72 Hours)



▲口▶▲圖▶▲圖▶▲圖▶ ▲国▶ ■ のQ@

Possible Source of Oscillations

Discretization-induced (discrete time, discrete state)

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

Delay-induced (discrete delay); Hopf bifurcation

New "Large Workflow" Assumptions

Provision resources based on individual submissions

 $N = jobs per user submission \gg M = max instances$

User-specified workflow "deadline"

 $T_{\text{deadline}} \gg \tau_{RT} > \tau_{RI} > \Delta t$

User-specified estimate of average job lifetime, τ_{RI} .

Meet deadline or run out of money; minimize waste and cost

Acknowledgments

Todd Miller @ UW - Madison Center for High Throughput Computing, HTCondor

Frank Würthwein @ UCSD Open Science Grid, Executive Director

Jeffery Dost @ UCSD Open Science Grid, Glidein Factory Operations

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Edgar Fajardo @ UCSD Open Science Grid, Software

Questions?



・ロト・4回ト・4回ト・4回ト・4回ト