

A MW Framework for Solving Recursive Economic Models

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Wealth Accumulation Example

Given initial capital stock x_0 , find $V(x_0)$

$$V(x_0) = \begin{cases} \max_{(c_t, l_t)} & \sum_{t=0}^{\infty} \beta^t u(c_t, l_t) \\ \text{s.t.} & x_{t+1} = x_t + f(x_t, l_t) - c_t \end{cases}$$

- c_t and l_t are consumption and labor supply at time t
- capital evolves according to $x_{t+1} = x_t + f(x_t, l_t) - c_t$
- β is the discount factor and $u(c_t, l_t)$ is the utility given consumption c_t and labor supply l_t
- $V(x)$ is the *value function* for $x_0 = x$

Dynamic Programming

As written, this is an optimization problem with infinitely many variables: $c_t, l_t, x_t, t = 0, 1, 2, \dots$, so as written it is impossible to solve.

But we can make use of the *dynamic programming principle*, based on the observation that the optimal objective $V(x_0)$ depends only on x_0 . Also note by the form of the objective and constraints, we have at the optimal values of x_t, c_t, l_t that

$$\begin{aligned} V(x_0) &= u(c_0, l_0) + \beta \sum_{t=0}^{\infty} \beta^t u(c_{t+1}, l_{t+1}) \\ &= u(c_0, l_0) + \beta V(x_1) \\ &= u(c_0, l_0) + \beta V(x_0 + f(x_0, l_0) - c_0). \end{aligned}$$

We can use this formula involving V to solve for the entire function V , not just find its value at a given x_0 .

Bellman Equation for $V(x)$

$$V(x) = \max_{(c,l)} u(c, l) + \beta V(x + f(x, l) - c) \quad (1)$$

- The function V is **unknown**
- Parametric dynamic programming: Approximate $V(x)$ by $\hat{V}(x; \mathbf{a})$, and solve for the parameters \mathbf{a} using the information in the Bellman equation.

- e.g., $\hat{V}(x; \mathbf{a}) = \sum_{j=0}^p a_j x^j$

- find $\mathbf{a} \in \mathbb{R}^p$ such that $\hat{V}(x; \mathbf{a})$ “approximately” satisfies the Bellman equation (1), on a finite grid of x values:

$$x_1, x_2, \dots, x_n.$$

Value Function Iteration

Step 0. *Initialization.* Choose functional form for $\hat{V}(x; \mathbf{a})$ and approximation grid $X = \{x_1, \dots, x_n\}$.

Make initial guess $\hat{V}(x; \mathbf{a}^0)$ and choose $\epsilon > 0$.

Step 1. *Maximization step.* Fix $\mathbf{a}^k = (a_j^k)_{j=1}^p$.

For $i = 1, \dots, n$, compute

$$v_i = T\hat{V}^k(x_i, \mathbf{a}^k) = \max_{(c_i, l_i)} u(c_i, l_i) + \beta \hat{V}(x_i^+, \mathbf{a}^k)$$

where $x_i^+ = x_i + f(x_i, l_i) - c_i$

Step 2. *Fitting step.* Fix c, l . Find \mathbf{a}^{k+1} s.t.

$$\mathbf{a}^{k+1} = \mathbf{argmin}_{\mathbf{a}} \|\hat{V}(x, \mathbf{a}) - v\|^2$$

Step 3. *Convergence.* If $\|\hat{V}(x, \mathbf{a}^{k+1}) - \hat{V}(x, \mathbf{a}^k)\|_{\infty} > \epsilon$, go to Step 1; otherwise stop and report solution.

Value Function Iteration in MW

Objective: Solve the Bellman equation (1)

MASTER: *Initialization.* Choose functional form for $\hat{V}(x; a)$ and approximation grid $X = \{x_1, \dots, x_n\}$.

Make initial guess $\hat{V}(x; a^0)$ and choose $\epsilon > 0$.

WORKER: *Maximization step.* Fix $a^k = (a_j^k)_{j=1}^p$.

For $i = 1, \dots, n$, compute (in parallel)

$$v_i = T\hat{V}^k(x_i, a^k) = \max_{(c_i, l_i)} u(c_i, l_i) + \beta \hat{V}(x_i^+, a^k)$$

MASTER: *Fitting step.* Fix c, l . Find a^{k+1} s.t.

$$a^{k+1} = \operatorname{argmin}_a \|\hat{V}(x, a) - v\|^2$$

MASTER: *Convergence.* If $\|\hat{V}(x, a^{k+1}) - \hat{V}(x, a^k)\|_\infty > \epsilon$, go to Step 1; otherwise stop and report solution.

MW Implementation Notes

- Each task finds the optimal (c_i, l_i) for a batch of x_i 's.
 - Calls a FORTRAN code (to demonstrate that we can!) to do minimizations.
 - Hot starting - the optimal (c_i, l_i) is usually a great starting point for (c_{i+1}, l_{i+1}) .
 - The task “wrapper” and the FORTRAN code communicate via files.

MW Implementation Notes

- `act_on_complete_task()` on the Master stores the v_i 's as they arrive from the workers. When all workers have reported, it solves the least-squares problem (fitting step) to find a^{k+1} .
 - Could still take a fitting step without waiting for all tasks to report, to avoid hangups if some workers go down.
 - Could adapt size of task (number of x_i 's in the batch) to accommodate workers of different speeds.

How Big Can These Get?

Judd: These models can get very Big!!!

- Investment Portfolio
 - d assets in the portfolio
 - $X_j = \{x_{j1}, \dots, x_{jn}\}$ represents j -th asset's position
 - state space: $X = X_1 \times X_2 \times \dots \times X_d$
 - transaction cost occurs when adjusting asset positions
- Dynamic Principal-Agent Problem
 - the CEO's performance is evaluated by multiple measures, e.g. stock price, annual profits, etc.
 - the company decides the CEO's compensation package
- Many other economic applications

Current and Future Work

- Adapting a Fortran90 code with a more complex representation for $\hat{V}(x, a)$, multidimensional x , “legacy” minimization routine.
- Dynamic Programming is
 - ubiquitous
 - compute-intensive,
 - algorithmically well suited to the master-worker paradigm supported by MW.
- We are investigating a suitable abstracted implementation of dynamic programming in MW: **MW-DP**.