

HW 3
CS 559

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(1)

1.

$$P_0(u) = (u^3 \ u^2 \ u \ 1) M \begin{pmatrix} P_0 \\ P_1 \\ P_2 \\ P_3 \end{pmatrix}$$

$$P_1(u) = (u^3 \ u^2 \ u \ 1) M \begin{pmatrix} P_1 \\ P_2 \\ P_3 \\ P_4 \end{pmatrix}$$

$$\Rightarrow P_0'(u) = (3u^2 \ 2u \ 1 \ 0) M \begin{pmatrix} P_0 \\ P_1 \\ P_2 \\ P_3 \end{pmatrix}$$

$$P_1'(u) = (3u^2 \ 2u \ 1 \ 0) M \begin{pmatrix} P_1 \\ P_2 \\ P_3 \\ P_4 \end{pmatrix}$$

$$\Rightarrow P_0''(u) = (6u \ 2 \ 0 \ 0) M \begin{pmatrix} P_0 \\ P_1 \\ P_2 \\ P_3 \end{pmatrix}$$

$$P_1''(u) = (6u \ 2 \ 0 \ 0) M \begin{pmatrix} P_1 \\ P_2 \\ P_3 \\ P_4 \end{pmatrix}$$

$$P_0'(1) = (3 \ 2 \ 1 \ 0) M \begin{pmatrix} P_0 \\ P_1 \\ P_2 \\ P_3 \end{pmatrix} = -3P_1 + 3P_3$$

$$P_1'(0) = (0 \ 0 \ 1 \ 0) M \begin{pmatrix} P_1 \\ P_2 \\ P_3 \\ P_4 \end{pmatrix} = -3P_1 + 3P_3$$

$$P_0''(1) = (6 \ 2 \ 0 \ 0) M \begin{pmatrix} P_0 \\ P_1 \\ P_2 \\ P_3 \end{pmatrix} = 6P_1 - 12P_2 + 6P_3$$

$$P_1''(0) = (0 \ 2 \ 0 \ 0) M \begin{pmatrix} P_1 \\ P_2 \\ P_3 \\ P_4 \end{pmatrix} = 6P_1 - 12P_2 + 6P_3$$

$\therefore P_0'(1) = P_1'(0)$ and $P_0''(1) = P_1''(0)$

The curve is C^2 continuous.

2.
$$P(u) = (u^3 \ u^2 \ u \ 1) \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix}$$

$$P(0) = d$$

$$P(1) = a + b + c + d$$

$$P\left(\frac{1}{2}\right) = \frac{1}{8}a + \frac{1}{4}b + \frac{1}{2}c + d$$

$$P'\left(\frac{1}{2}\right) = \frac{3}{4}a + b + c$$

$$\Rightarrow \begin{pmatrix} P(0) \\ P(1) \\ P\left(\frac{1}{2}\right) \\ P'\left(\frac{1}{2}\right) \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 1 \\ \frac{1}{8} & \frac{1}{4} & \frac{1}{2} & 1 \\ \frac{3}{4} & 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} = \begin{pmatrix} -4 & 4 & 0 & -4 \\ 8 & -4 & -4 & 6 \\ -5 & 1 & 4 & -2 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} P(0) \\ P(1) \\ P\left(\frac{1}{2}\right) \\ P'\left(\frac{1}{2}\right) \end{pmatrix}$$

3.

$$P(u) = (u^3 \ u^2 \ u \ 1) \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix}$$

$$P(0) = d$$

$$P\left(\frac{1}{3}\right) = \frac{1}{27}a + \frac{1}{9}b + \frac{1}{3}c + d$$

$$P\left(\frac{2}{3}\right) = \frac{8}{27}a + \frac{4}{9}b + \frac{2}{3}c + d$$

$$P(1) = a + b + c + d$$

$$\text{So } \begin{pmatrix} p(0) \\ p(\frac{1}{3}) \\ p(\frac{2}{3}) \\ p(1) \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 1 \\ \frac{1}{27} & \frac{1}{9} & \frac{1}{3} & 1 \\ \frac{8}{27} & \frac{4}{9} & \frac{2}{3} & 1 \\ 1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} = \begin{pmatrix} -\frac{9}{2} & \frac{27}{2} & -\frac{27}{2} & \frac{9}{2} \\ 9 & -\frac{45}{2} & 18 & -\frac{9}{2} \\ -\frac{11}{2} & 9 & -\frac{9}{2} & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} p(0) \\ p(\frac{1}{3}) \\ p(\frac{2}{3}) \\ p(1) \end{pmatrix}$$

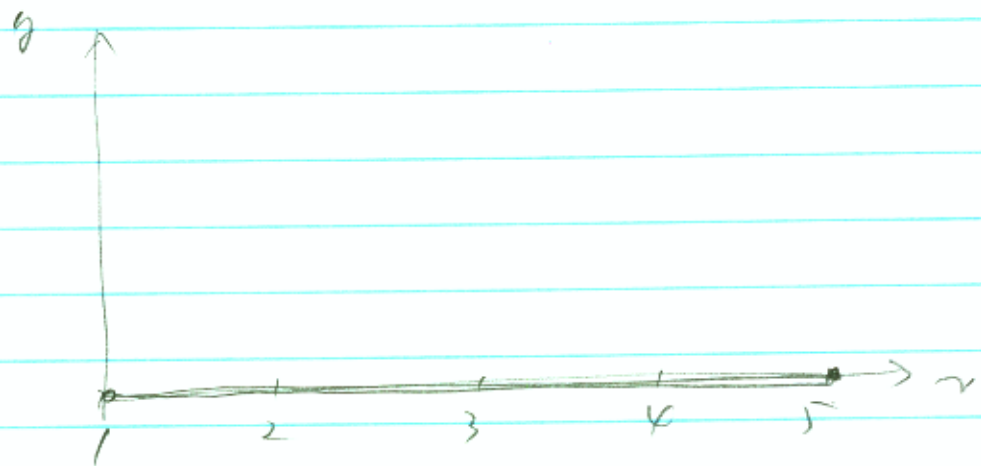
$$\varphi_1 \quad p(u) = (u^4 \ u^3 \ u^2 \ u \ 1) \begin{pmatrix} a \\ b \\ c \\ d \\ e \end{pmatrix}$$

$$\begin{pmatrix} p(0) \\ p(\frac{1}{4}) \\ p(\frac{1}{2}) \\ p(\frac{3}{4}) \\ p(1) \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 0 & 1 \\ \frac{1}{256} & \frac{1}{64} & \frac{1}{16} & \frac{1}{4} & 1 \\ \frac{1}{16} & \frac{1}{8} & \frac{1}{4} & \frac{1}{2} & 1 \\ \frac{81}{256} & \frac{27}{64} & \frac{9}{16} & \frac{3}{4} & 1 \\ 1 & 1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \\ d \\ e \end{pmatrix}$$

$$\text{So } \begin{pmatrix} a \\ b \\ c \\ d \\ e \end{pmatrix} = \begin{pmatrix} \frac{32}{3} & -\frac{128}{3} & 64 & -\frac{128}{3} & \frac{32}{3} \\ -\frac{80}{3} & 96 & -128 & \frac{224}{3} & -16 \\ \frac{70}{3} & -\frac{208}{3} & 76 & -\frac{112}{3} & \frac{22}{3} \\ -\frac{25}{3} & 16 & -12 & \frac{16}{3} & -1 \\ 1 & 0 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} p(0) \\ p(\frac{1}{4}) \\ p(\frac{1}{2}) \\ p(\frac{3}{4}) \\ p(1) \end{pmatrix}$$

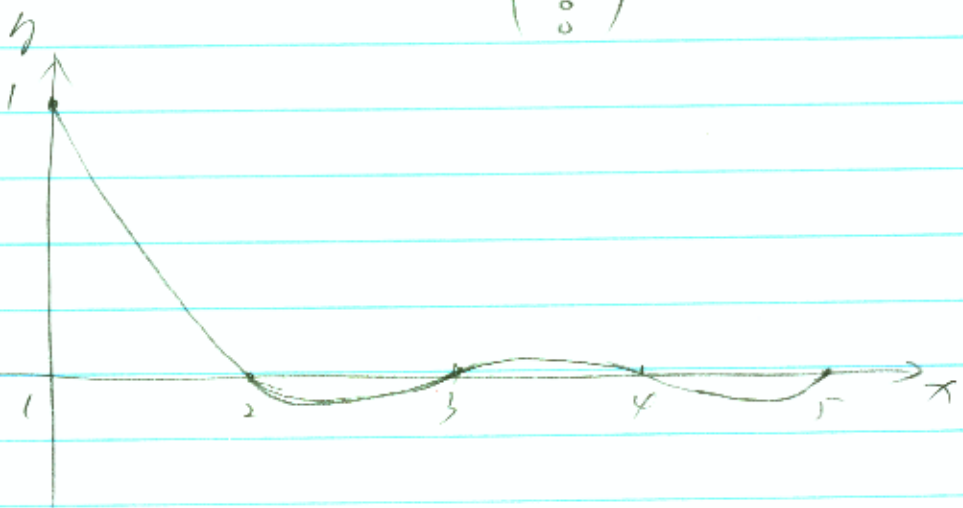
5. For control points (1, 0), (2, 0), (3, 0), (4, 0) & (5, 0)

$$\left\{ \begin{aligned} x(u) &= (u^4 \ u^3 \ u^2 \ u \ 1) M \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{pmatrix} = 4u + 1 \\ y(u) &= (u^4 \ u^3 \ u^2 \ u \ 1) M \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} = 0 \end{aligned} \right.$$



For control points (1, 1), (2, 0), (3, 0), (4, 0) & (5, 0)

$$\left\{ \begin{aligned} x(u) &= (u^4 \ u^3 \ u^2 \ u \ 1) M \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{pmatrix} = 4u + 1 \\ y(u) &= (u^4 \ u^3 \ u^2 \ u \ 1) M \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \frac{32}{3}u^4 - \frac{128}{3}u^3 + 64u^2 - \frac{128}{3}u + \frac{32}{3} \end{aligned} \right.$$



⑤
① The computation of higher order curve is much more expensive.

② The higher order curve has less locality in control. A small change to one control point can cause big change to the whole curve.